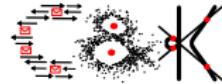


The k -variance problem



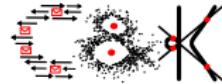
Orthogonal projections

- If $V \subseteq \mathbb{R}^d$, then $V^\perp := \{y \in \mathbb{R}^d \mid \forall x \in V : \langle y, x \rangle = 0\}$ is the orthogonal complement of V
- $V \cap V^\perp = \{0\}$ and for all $x \in \mathbb{R}^d$ there exist unique $x' \in V, x'' \in V^\perp$ with $x = x' + x''$
- $\pi_V : \mathbb{R}^d \rightarrow V, \pi_V(x) = x'$, orthogonal projection onto V , x'' denoted $\pi_V(x)^\perp$.
- If $\dim(V) = 1, V = \text{span}(v)$, then

$$\pi_V(x) = \frac{\langle x, v \rangle}{\langle v, v \rangle} v \quad \text{and} \quad \pi_V(x)^\perp = x - \frac{\langle x, v \rangle}{\langle v, v \rangle} v$$



The k -variance problem



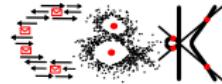
Problem 5.1 (k -variance problem)

Given $P \subset \mathbb{R}^d$, $|P| = n$ and $k \in \mathbb{N}$, Find the k -dimensional subspace V_k that minimizes

$$D(P, V) := \sum_{p \in P} \|p - \pi_V(p)\|^2.$$

The subspace V_k is called the (k -dimensional) singular value decomposition of P .

Characterization of optimal subspace



Lemma 5.2

For all $P \subset \mathbb{R}^d$

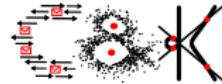
$$V_k = \operatorname{argmin}_{V: \dim(V)=k} \{D(P, V)\}$$

$$\Leftrightarrow V_k = \operatorname{argmax}_{V: \dim(V)=k} \left\{ \sum_{p \in P} \|\pi_V(p)\|^2 \right\}.$$

More generally, for every subspace $V \subseteq \mathbb{R}^d$

$$D(P, V) = \sum_{q \in P} \|q\|^2 - \sum_{q \in P} \|\pi_V(q)\|^2.$$

Complexity and relation to k -means



Theorem 5.3

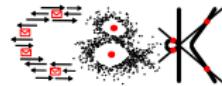
For every $P \subset \mathbb{R}^d$ and $k \in \mathbb{N}$ the subspace V_k minimizing $D(P, V)$ can be computed efficiently.

Lemma 5.4

For every $P \subset \mathbb{R}^d$ and $k \in \mathbb{N}$

$$D(P, V_k) \leq \text{opt}_k(P).$$

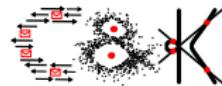
Spectral algorithms



Spectral algorithms

Given $P \subset \mathbb{R}^d$,

- 1 compute the singular value decomposition V_k , i.e. the subspace minimizing $D(P, V)$,
- 2 solve your favorite clustering problem with your favorite algorithm on input $\pi_{V_k}(P) := \{\pi_{V_k}(p) : p \in P\}$,
- 3 return the solution found in the previous step.



Definition 5.5

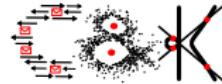
Let $V \subseteq \mathbb{R}^d$ be a k -dimensional subspace of \mathbb{R}^d and let $B = \{v_1, \dots, v_k\}$ be a basis of V . Basis B is an orthonormal basis (ONB) of V if

- 1 $\|v_i\| = 1, i = 1, \dots, k$
- 2 $\langle v_i, v_j \rangle = 0$ for $i \neq j, i, j = 1, \dots, n$.

Theorem 5.6

Every subspace $V \subseteq \mathbb{R}^d$ has an orthonormal basis. Moreover, any orthonormal basis of V can be extended to an orthonormal basis of \mathbb{R}^d .

Length-preserving linear maps

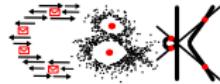


- $V \subseteq \mathbb{R}^d$ subspace with orthonormal basis $B_V = \{v_1, \dots, v_k\}$.
- $U \in \mathbb{R}^{k \times d}$ matrix with rows v_1^T, \dots, v_k^T .
- Π_V denotes function $\Pi_V : \mathbb{R}^d \rightarrow \mathbb{R}^k, x \mapsto U \cdot x$

Theorem 5.7

The linear function Π_V has the following properties:

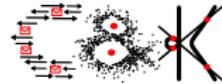
- 1 Π_V is surjective.
- 2 Π_V is length-preserving on V , i.e. for all $x \in V : \|x\| = \|\Pi_V(x)\|$.



Spectral algorithms

Given $P \subset \mathbb{R}^d$,

- 1 compute the singular value decomposition V_k , i.e. the subspace minimizing $D(P, V)$,
- 2 solve your favorite clustering problem with your favorite algorithm on input $\pi_{V_k}(P) := \{\pi_{V_k}(p) : p \in P\}$, i.e. compute an orthonormal basis for V_k and apply your favorite clustering algorithm on the set $\Pi_{V_k}(\pi_{V_k}(P))$
- 3 return the solution found in the previous step.



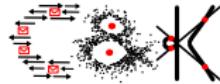
Lemma 5.8

Let $P \subset \mathbb{R}^d$ and let V be an arbitrary k -dimensional subspace of \mathbb{R}^d . Then

$$opt_k(\pi_V(P)) \leq opt_k(P),$$

where $opt_k(P)$ denotes the cost of an optimal solution of k -means with input P .

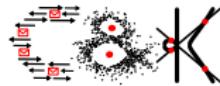
k -variance and k -means



Lemma 5.9

Let $P \subset \mathbb{R}^d$ and let V be an arbitrary k -dimensional subspace of \mathbb{R}^d . Assume $\hat{\mathcal{C}} = \{\hat{C}_1, \dots, \hat{C}_k\}$ is a k -clustering of $\pi_V(P)$ and denote by $\mathcal{C} := \{C_1, \dots, C_k\}$ with $C_i := \{p \in P : \pi_V(p) \in \hat{C}_i\}$, the corresponding k -clustering of P . Then

$$\text{cost}(\pi_V(P), \hat{\mathcal{C}}) \leq \text{cost}(P, \mathcal{C}) \leq \text{cost}(\pi_V(P), \hat{\mathcal{C}}) + D(P, V).$$



Spectral algorithms

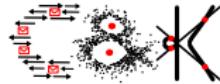
Given $P \subset \mathbb{R}^d$,

- 1 compute the singular value decomposition V_k , i.e. the subspace minimizing $D(P, C)$,
- 2 solve your favorite clustering problem with your favorite algorithm on input $\pi_{V_k}(P) := \{\pi_{V_k}(p) : p \in P\}$,
- 3 return the solution found in the previous step.

Theorem 5.10

Let $P \subset \mathbb{R}^d$ and let V_k be the k -dimensional subspace of \mathbb{R}^d minimizing $D(P, V)$. If $\hat{\mathcal{C}}$ is a γ -approximate k -clustering for $\pi_{V_k}(P)$, then the corresponding k -clustering \mathcal{C} as defined in the previous lemma is a $(\gamma + 1)$ -approximate k -clustering for P .

An exact algorithm for k -means



EXACT-K-MEANS(P, k)

Compute the set K of sets of t hyperplanes with $k \leq t \leq \binom{k}{2}$ where each hyperplane contains d affinely independent points from P ;

for $S \in K$ **do**

check that S defines an arrangement of exactly k cells;

for all assignments a_S **of points of** P **on hyperplanes in** S **to cells do**

for all cells do

| compute the centroid of points of P in the cell;

end

$C_{S,a_S} :=$ set of centroids computed in the previous step;

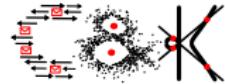
end

$C_S := \operatorname{argmin}_{C_{S,a_S}} \{D(P, C_{S,a_S})\};$

end

return $\operatorname{argmin}_{C_S} \{D(P, C_S)\};$

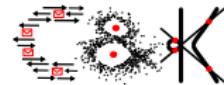
An exact algorithm for k -means



Theorem 5.11

Algorithm EXACT-K-MEANS solves the k -means problem optimally in time $O(n^{dk^2/2})$.

A spectral approximation algorithm



SPECTRAL-K-MEANS(P, k)

Compute $V_k := \operatorname{argmin}_{V: \dim(V)=k} \{D(P, V)\}$;

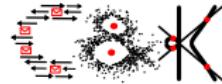
$\bar{C} := \text{EXACT-K-MEANS}(\pi_{V_k}(P), k)$;

return \bar{C} ;

Theorem 5.12

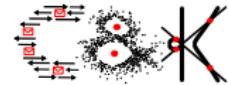
SPECTRAL-K-MEANS *is an approximation algorithm for the k-means problem with running time $O(n \cdot d^2 + n^{k^3/2})$ and approximation factor 2.*

Matrix representation of point sets



- $P = \{p_1, \dots, p_n\} \subset \mathbb{R}^d$
- matrix $A \in \mathbb{R}^{d \times n}$ with columns p_i called *matrix representation* of P
- rows of $A^T \in \mathbb{R}^{n \times d}$ are p_i^T
- for every $v \in \mathbb{R}^d$:
 - $A^T \cdot v = (\langle p_1, v \rangle, \dots, \langle p_n, v \rangle)^T \in \mathbb{R}^n$
 - $\|A^T \cdot v\|^2 = v^T \cdot A \cdot A^T \cdot v = \sum_{i=1}^n \langle p_i, v \rangle^2$

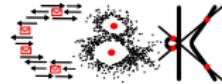
Characterization of k -variance solutions



Theorem 5.13

For every set of points $P \subset \mathbb{R}^d$, $|P| = n$, with matrix representation $A \in \mathbb{R}^{d \times n}$:

$$\operatorname{argmax}_{V: \dim(V)=k} \left\{ \sum_{p \in P} \|\pi_V(p)\|^2 \right\} = \operatorname{argmax}_{\text{ONB } B : |B|=k} \left\{ \sum_{v \in B} v^T \cdot A \cdot A^T \cdot v \right\}$$



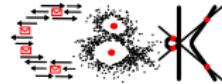
Definition 5.14

Let $M \in \mathbb{R}^{d \times d}$, $\lambda \in \mathbb{R}$ and $v \in \mathbb{R}^d$, $v \neq 0$. Then λ is called an eigenvalue of M to eigenvector v (and vice versa) if $M \cdot v = \lambda \cdot v$.

Theorem 5.15

For every $A \in \mathbb{R}^{d \times n}$ the matrix $M = A \cdot A^T \in \mathbb{R}^{d \times d}$ has non-negative eigenvalues $\lambda_1 \geq \dots \geq \lambda_d \geq 0$. Moreover, there is an orthonormal basis $B = \{v_1, \dots, v_d\}$ such that λ_i is an eigenvalue of M to eigenvector v_i , $i = 1, \dots, d$.

Solutions to the k -variance problem

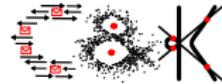


Theorem 5.16

Let $P \subset \mathbb{R}^d$ be a finite set of points with matrix representation $A \in \mathbb{R}^{d \times n}$ and $k \in \mathbb{N}$. If $A \cdot A^T$ has eigenvalues $\lambda_1 \geq \dots \geq \lambda_d$ and $B = \{v_1, \dots, v_d\}$ is an orthonormal basis consisting of eigenvectors, i.e. v_i is an eigenvector to eigenvalue λ_i , $i = 1 \dots, d$, then

$$\text{span}\{v_1, \dots, v_k\} = \underset{V: \dim(V)=k}{\operatorname{argmin}} \{D(P, V)\}.$$

Singular values and vectors



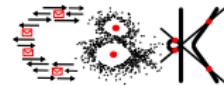
- $M \in \mathbb{R}^{n \times d}$,
- case $d = n$: $v \in \mathbb{R}^d$ eigenvector to eigenvalue σ if
 $M \cdot v = \sigma \cdot v$
- generalization to $n \neq d$?
- can one compute eigenvectors and eigenvalues of $A \cdot A^T$ without computing the matrix product?

Singular vectors and singular values

$\sigma \in \mathbb{R}$ is called singular value of M with corresponding singular vectors $v \in \mathbb{R}^d$, $u \in \mathbb{R}^n$ if

- 1 $M \cdot v = \sigma \cdot u$
- 2 $u^T \cdot M = \sigma \cdot v^T$.

Eigenvectors and singular vectors



Lemma 5.17

Let $M \in \mathbb{R}^{n \times d}$. Then $\sigma \in \mathbb{R}$ is a singular value of M with corresponding singular vectors $v \in \mathbb{R}^d$ and $u \in \mathbb{R}^n$ if and only if

- 1 σ^2 is an eigenvalue of $M^T \cdot M$,
- 2 v is a right eigenvector of $M^T \cdot M$ to eigenvalue σ^2 ,
- 3 u^T is a left eigenvector of $M \cdot M^T$ to eigenvalue σ^2 .